

# On Adaptive Patankar Runge–Kutta methods

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We apply Patankar Runge–Kutta methods to  $y' = M(y)y$  and focus on the case where  $M(y)$  is a graph Laplacian as the resulting scheme will preserve positivity and total mass. The second order Patankar Heun method is tested using four test problems (stiff and non-stiff) cast into this form. The local error is estimated and the step size is chosen adaptively. Concerning accuracy and efficiency, the results are comparable to those obtained with a traditional L-stable, second order Rosenbrock method.

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## 1 Definition of the Scheme

Consider the autonomous initial value problem

$$y'(t) = M(y(t))y(t), \quad y(t_0) = t_0, \quad t \in [t_0, t_{\text{end}}], \tag{1}$$

with  $y(t) \in \mathbb{R}^n$  and  $M(y(t)) \in \mathbb{R}^{n \times n}$ . If  $M(y)$  is a graph Laplacian, then positivity and total mass are conserved by the analytical solution  $y(t)$ , see [1] for details and other schemes.

A Patankar Runge–Kutta method for (1) takes the form

$$\begin{aligned} y^{(k)} &= y^n + h \sum_{\nu=1}^{k-1} a_{k\nu} M(y^{(\nu)}) \text{diag}(w_\nu) y^{(k)} \\ y^{n+1} &= y^n + h \sum_{k=1}^s b_k M(y^{(k)}) \text{diag}(\hat{w}) y^{n+1} \end{aligned} \tag{2}$$

where  $w_\nu$  and  $\hat{w}$  are so-called Patankar weight. Autonomous production-destruction systems can be written in the form (1) and the scheme (2) is then equivalent to existing formulations of Patankar Runge-Kutta methods [2, 3].

## 2 Numerical Experiments

In this note, we focus exclusively on the robust second order Patankar Heun method [2]

$$\begin{aligned} y^{(2)} &= y^n + hM(y^n)y^{(2)}, \\ y^{n+1} &= y^n + \frac{h}{2} \left( M(y^n) \text{diag}\left(\frac{y^n}{y^{(2)}}\right) + M(y^{(2)}) \right) y^{n+1}. \end{aligned}$$

Schemes of order 3 (cf. [3]) and higher (cf. [4]) will be considered in future work.

The following problems are considered:

1. Lotka, A non-stiff problem of Lotka-Volterra type

$$\begin{pmatrix} y_1' \\ y_2' \end{pmatrix} = \begin{pmatrix} 1 - y_2 & 0 \\ y_2 & -1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \quad y(0) = [1, 2]^\top, \quad t \in [0, 10]. \tag{3}$$

This problem does not originate from a production-destruction system (although a first integral exists) and hence  $M(y)$  is not a graph Laplacian. Consequently, the Patankar method is not guaranteed to preserve quantities.

2. Robertson, cf. [5], with  $k_1 = 0.04$ ,  $k_2 = 3 \cdot 10^7$  and  $k_3 = 10^4$  in the form

$$\begin{pmatrix} y_1' \\ y_2' \\ y_3' \end{pmatrix} = \begin{pmatrix} -k_1 & k_3 y_2 & 0 \\ k_1 & -k_2 y_2 - k_3 y_3 & 0 \\ 0 & k_2 y_2 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}, \quad y(0) = [1, 0, 0]^\top, \quad t \in [0, 10^5]. \tag{4}$$

Here,  $M(y)$  is a graph Laplacian. The numerical solution will be positive and the total mass is conserving. Usually, one has  $t_{\text{end}} = 10^{11}$ . This works, too – with smaller errors but we want to see the errors to be able to evaluate the adaptive stepping.

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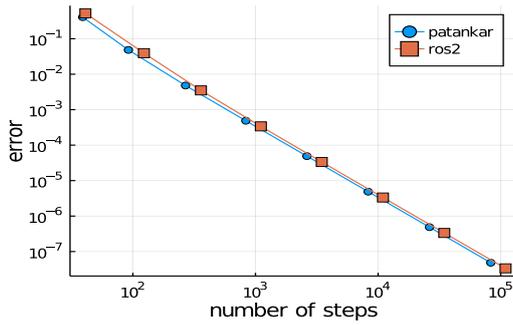


Fig. 1: Results for Lotka-Volterra (3).

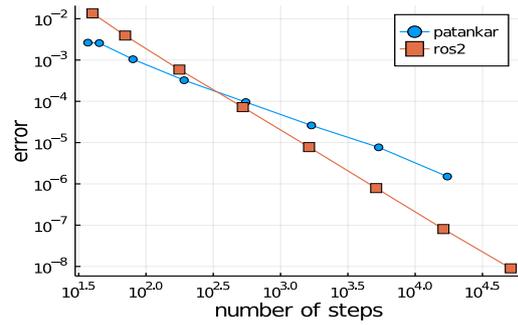


Fig. 2: Results for the Robertson problem (4).

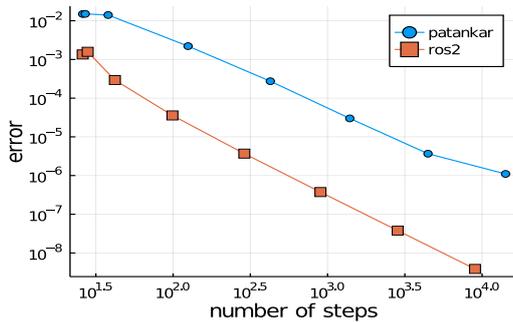


Fig. 3: Results for the pollution problem.

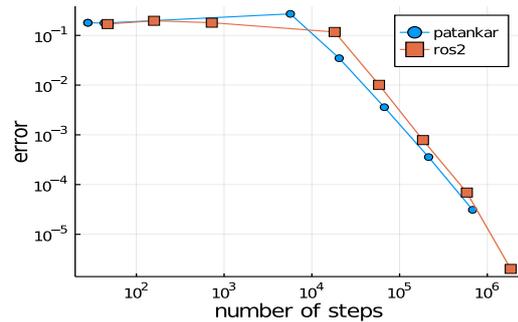


Fig. 4: Results for MAPK.

3. Pollu, a stiff system of 20 components, taken from cf. [5]. This is a production-destruction system which be written (in several different ways) in the form (1) with a graph Laplacian  $M(y)$ .
4. MAPK, taken from [1], the origin is [6], consisting of six equations. It has a graph Laplacian and it is mildly stiff.

The code has been implemented in Julia and can be downloaded from <https://www2.mathematik.uni-halle.de/podhaisky/software/aprk/>. Step size control is standard and based on the first order error estimate  $y^{n+1} - y^{(2)}$ . Figures 1-4 shows that the adaptive code works in all cases. Compared with the two-stage second order Rosenbrock method ROS2 [7], the Patankar Runge–Kutta shows a similar accuracy except for problem Pollu.

### 3 Conclusion

The proposed adaptive second order scheme works robustly. Note, the Patankar Runge–Kutta method outperforms ROS2 for low tolerances in the Robertson problem – in a regime, where positivity of the solution is crucial. A detailed analysis and the use of higher order Patankar Runge–Kutta methods is future work.

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